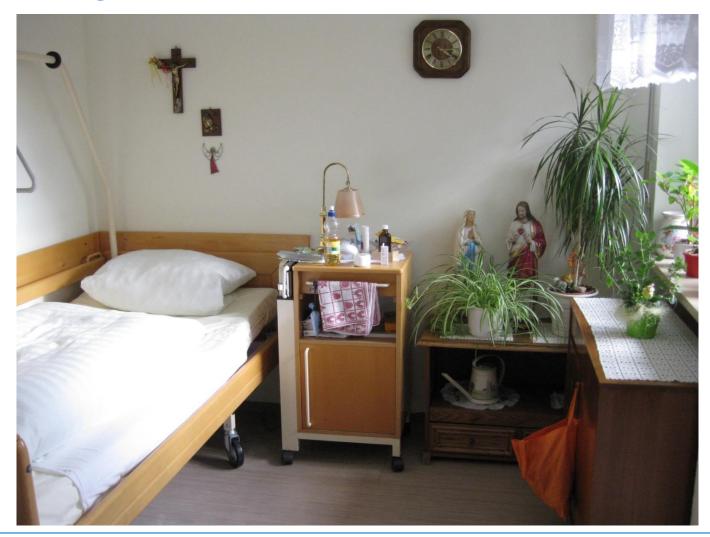
**Human Factors Ambient Design** for **Aging Society Chair for Building Realization and Robotics** Thomas Bock, Technische Universität München (TUM)





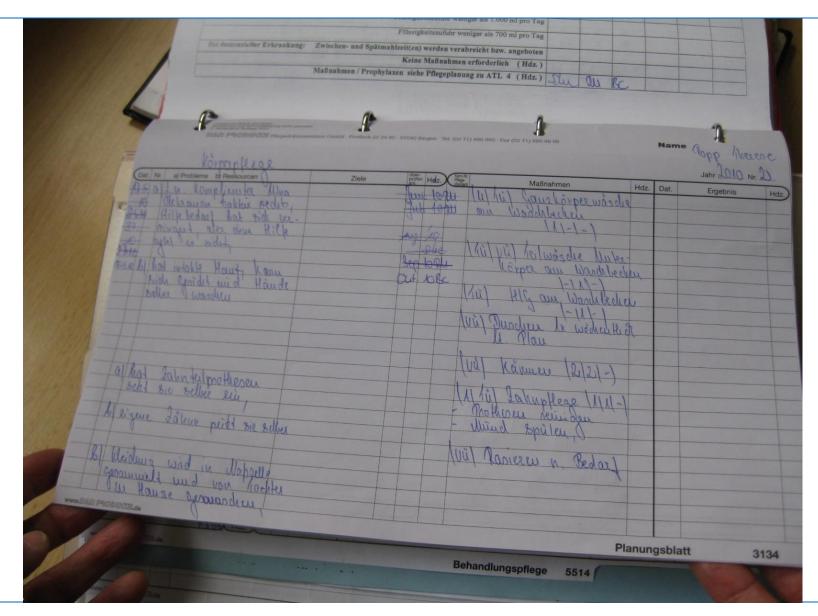
## **Existing Situation in German Care Facilities**







Chair for Building Realization and Robotics Prof. Prof. SRSTU Dr.-Ing./Univ. Tokio T. Bock



























Chair for Building Realization and Robotics Prof. Prof. SRSTU Dr.-Ing./Univ. Tokio T. Bock







#### **Transfer Systems Ceiling**







#### Homemaking and Entertainment Robots (Home Service Robots)

- Edutainment robots are designed to amuse, communicate, perform simple tasks in the household – they can also be used as a control interface (for example Wakamura)
- Homemaking Robots are robots which take over simple tasks as cleaning, transporting of objects or informing about intruders or the pets' well-being



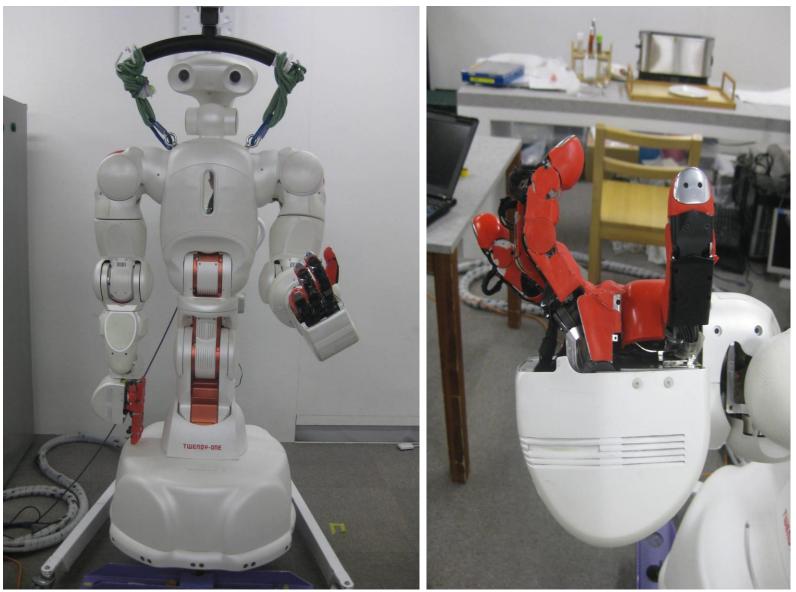
#### Concept of future city - technological development

**Health care** 



Robots are changing the medical industry and hospitals forever, in what many say is a technology overhaul that addresses shortages of staff and improvements to the level of service for patients, especially for hospitals farther away from experts.

# ТШП





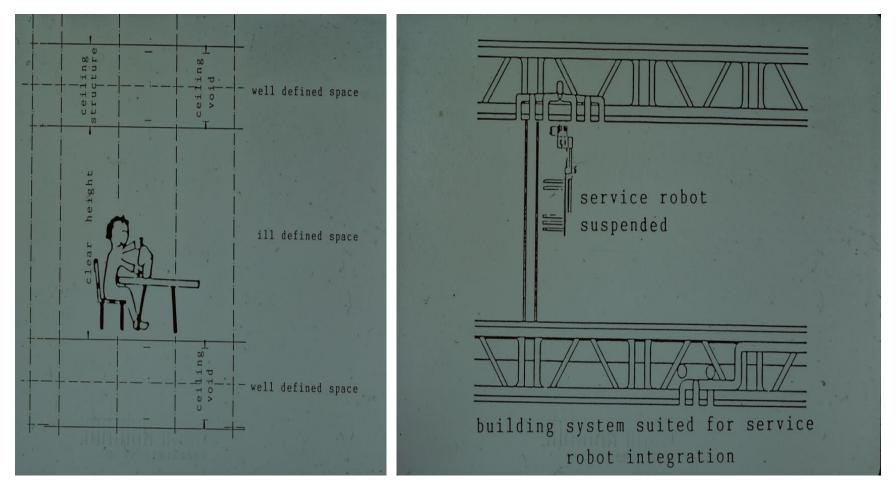
#### **Ausblick**







# **Robot Oriented Design – Dissertation UoT Bock** 1984-89



#### vision from the mid 80's from Comics to Reality: Life Support Systems



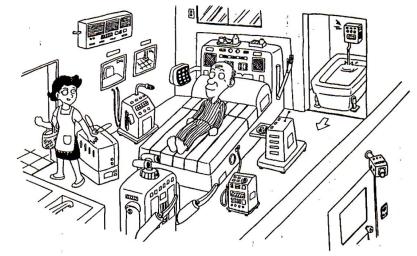
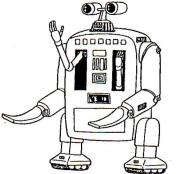
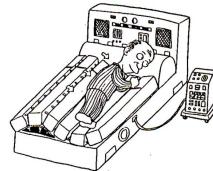
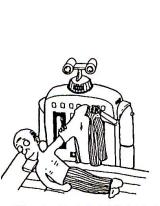


図7-1 在宅介護の概念構想 (作成:黒沢R&D技術事務所,'85.5,以下同じ)







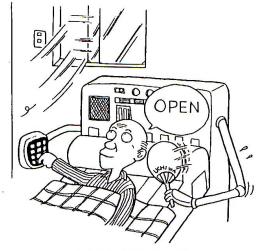


図7-4 身廻り介助(着衣交換)



図7-5 環境制御の1例









#### Vision from the 80's

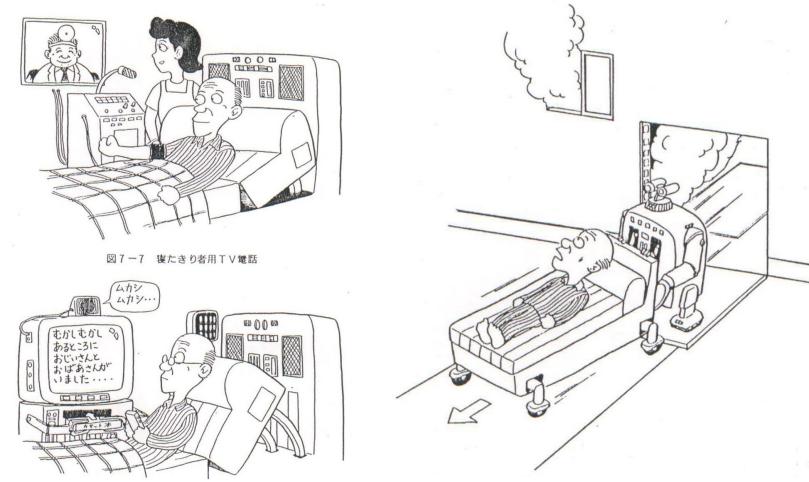


Image: T. Bock



#### Vision from the 80's



J



図7-12 入浴介助





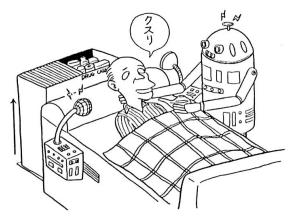


図7-14 与薬介助





Image: T. Bock

3 D



#### Vision from the 80's

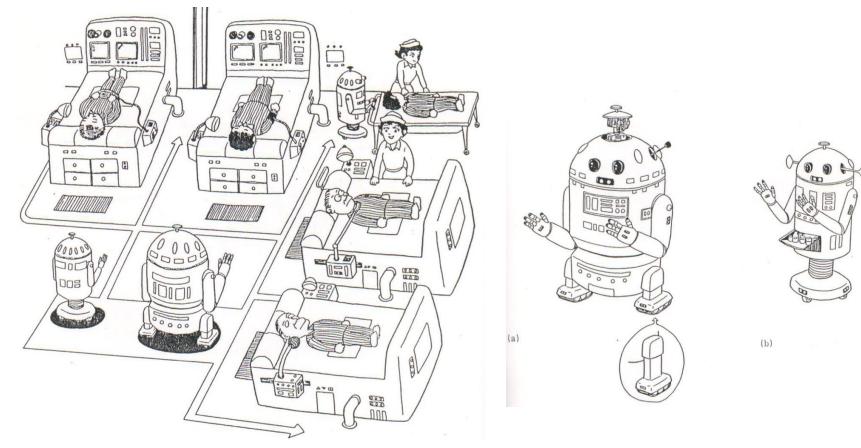


Image: T. Bock

16.11.2018





#### 16.11.2018



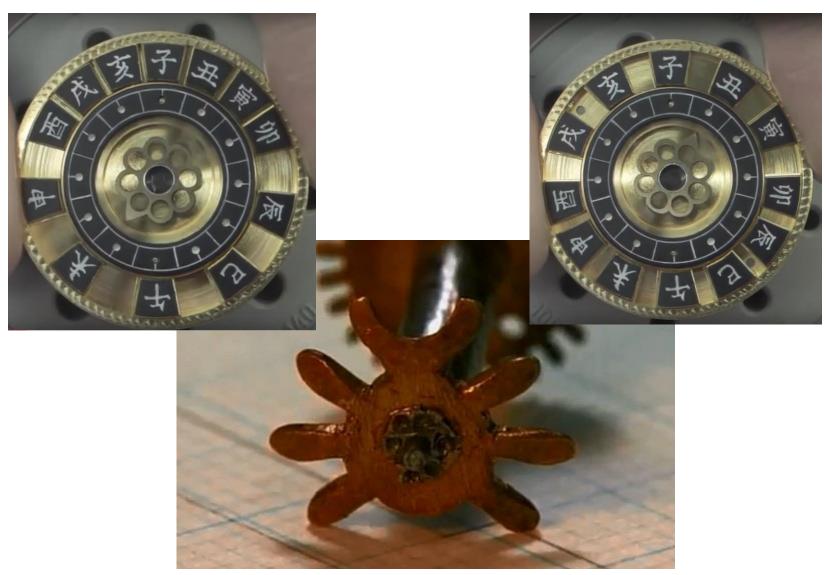








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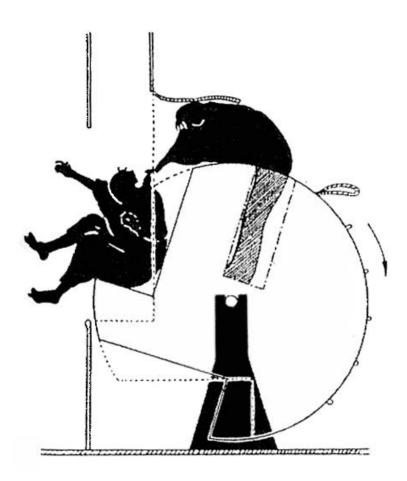


Wadokei clock, designed by the Japanese inventor Hisashige Tanaka in This clock is designated as an important cultural asset by Japanese government. Source: <a href="https://www.youtube.com/watch?v=l6r24uKbWug">https://www.youtube.com/watch?v=l6r24uKbWug</a>

http://watchesbysjx.com/2017/05/portrait-masahiro-kikuno-japanese-watchmaker.html

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### Gattai:









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16.11.2018

# ПΠ

# SYSTEMS: LIFE SUPPORT SYSTEM **ROBOTIC AMBIENCE FOR** INDEPENDANT LIVING, WORKING, MOBILITY

**NEW SOCIO TECHNICAL** 

### **BR2** Lab



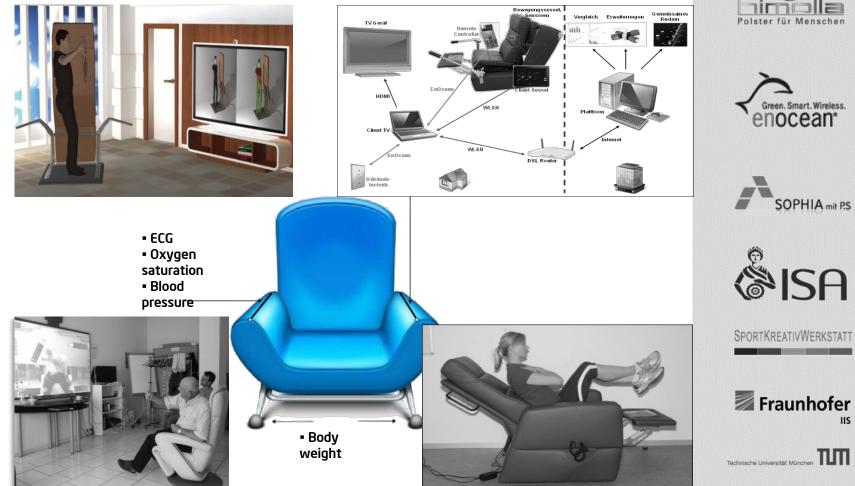








#### **Rejuvenation Oriented Design ROD GEWOS – Gesund Wohnen mit Stil HyLive: Healthy living with style**





#### **Rejuvenation Oriented Design ROD GEWOS – Gesund Wohnen mit Stil HyLive: Healthy living with style**





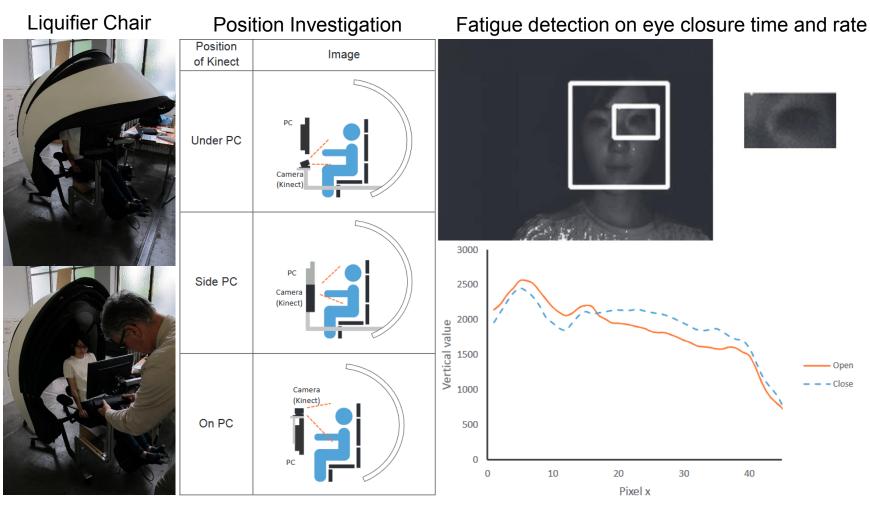
Erdt, S., Linner, T., Herdener, L., Kreitmair, M., Rieß, J., Roalter, L., ... & Kranz, M. (2012). Systematische Entwicklung eines komplexen Assistenzsystems zur Gesundheitsförderung am Beispiel des GEWOS-Bewegungssessels. Technik für ein selbstbestimmtes Leben.





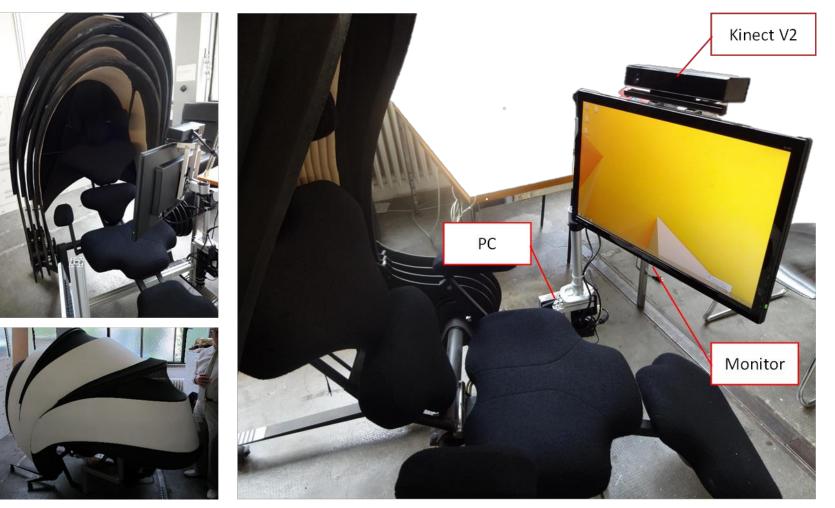
37

#### Rejuvenation Oriented Design ROD Fatigue/depression prevention by emotion detection



Nakaso, S., Güttler, J., Mita, A., & Bock, T. A Fatigue Detection System implemented in an Office Deployable Gateway based on Eye Movement.

# **Rejuvenation Oriented Design ROD** Fatigue detection



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11/16/2018



#### **Mechatronic Wall**



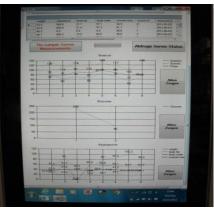
Modularity on "Room Level"







# Modularity on Software & Service Level



Modularity on "Wall Level"

Modular functional Ad-ons



Modularity on Cabinet Level

# **Cross-disciplinarity**



br

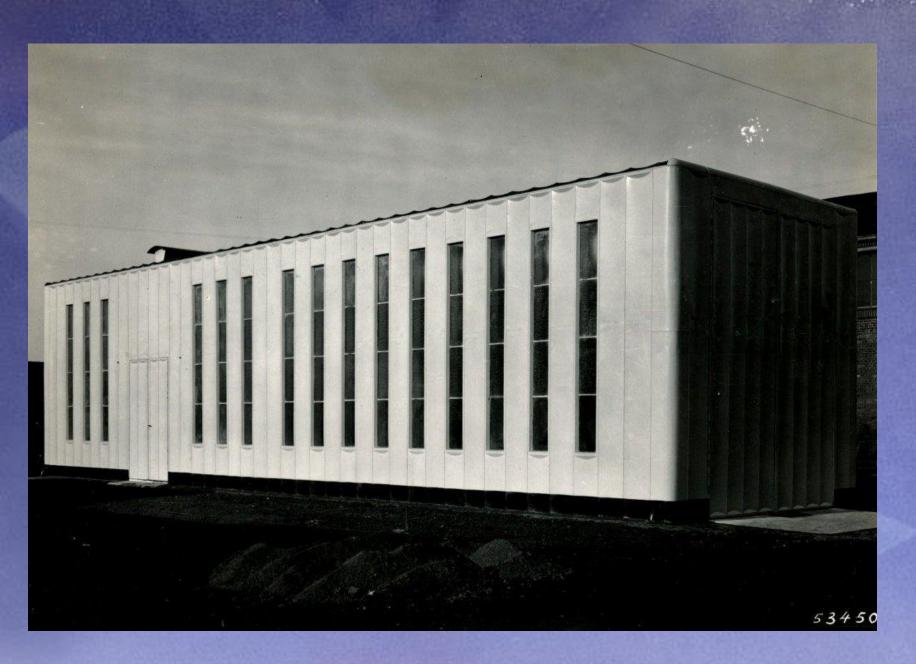
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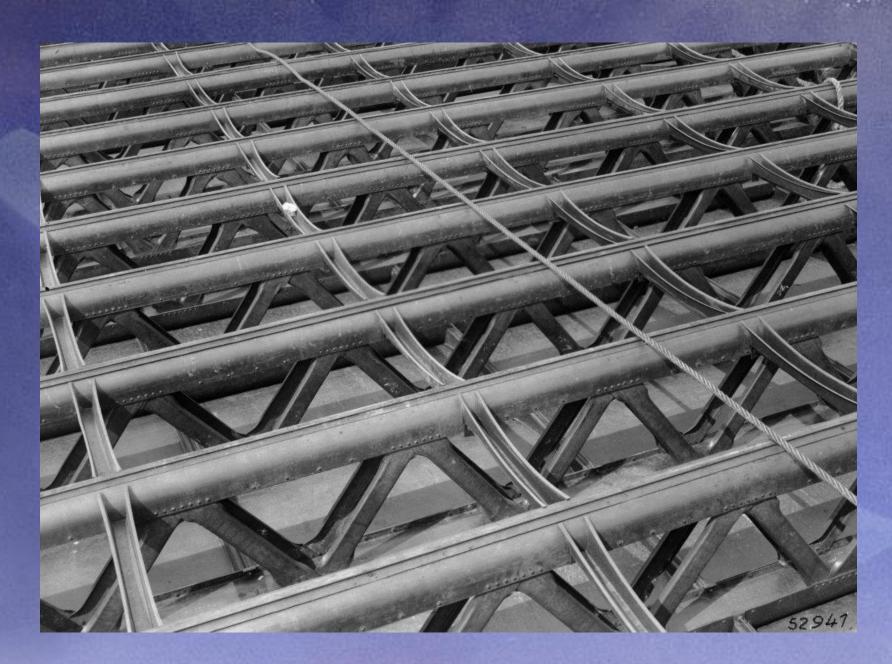
## Junkers Ju 52/3m Berlin Tempelhof 2011 at Munich airport



#### **Junkers Steel Furniture**



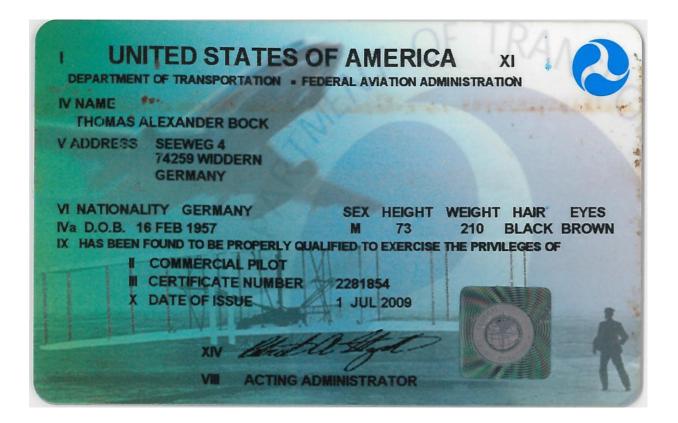
**Painting Booth** 



**Roof Structure** 

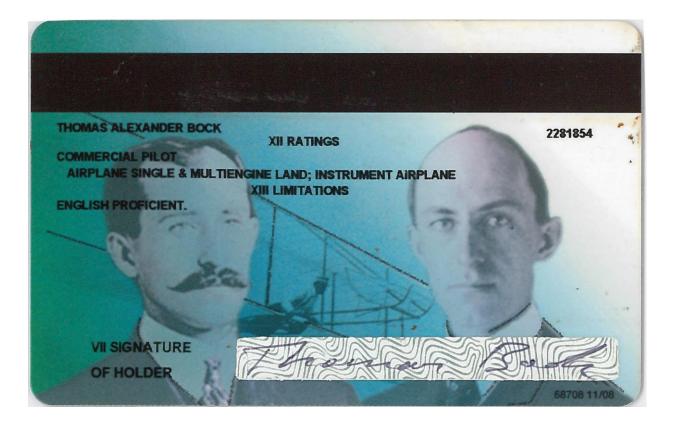
# ТЛП

# FAA Commercial Pilot License, IFR, MEL (1979)





### **FAA Commercial Pilot License**





# **Pilot's cockpits, aircraft technology III** CPL, IFR, MEL at Flight Proficiency Dallas Love Field, 1979

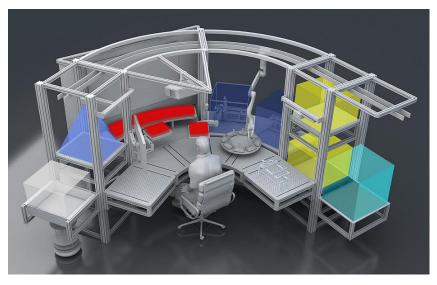


Image: Airbus A380 cockpit By Naddsy [CC BY 2.0 (httpcreativecommons.orglicensesby2.0)], via Wikimedia Commons

Image: Antonov An-124 cockpit By Dmitry Petrov (httprussianplanes.netID50699) [CC BY-SA 3.0 (httpscreativecommons.orglicensesby-sa3.0) or CC BY-SA 3.0 (httpscreativecommons.orglicensesby-sa3.0)], via Wikimedia Commons

#### **Rejuvenation Oriented Design ROD** usa<sup>2</sup>:

ubiquitäres selbstbestimmtes arbeiten im alter (Robot Assisted Working & Cloud Manufacturing)









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# **R**ejuvenation Oriented Design ROD Utilization of Robotic Elements, gesture detection/control

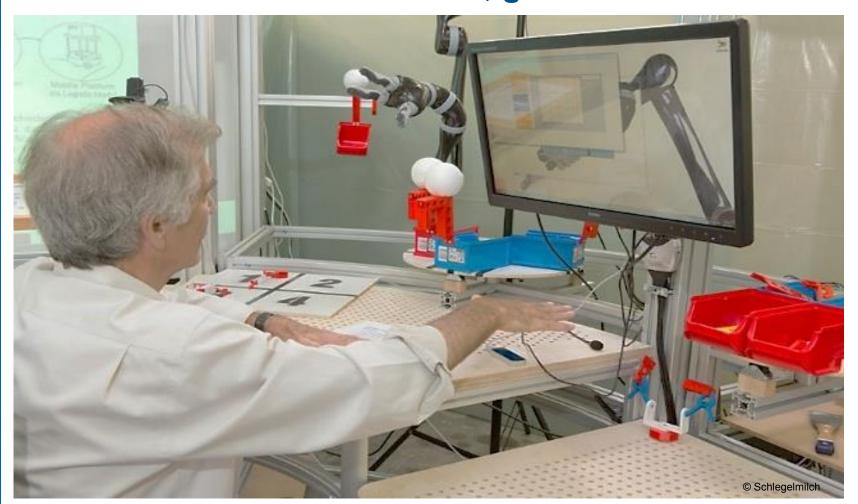


Image: This work has been developed in the project USA<sup>2</sup> - the research project was finaced by the German Federal Ministry of Education and Research (BMBF, grant number: 16SV6191) within the Human-Technology Interaction (MTI) program/ technological development by Chair of Building Realisation and Robotics

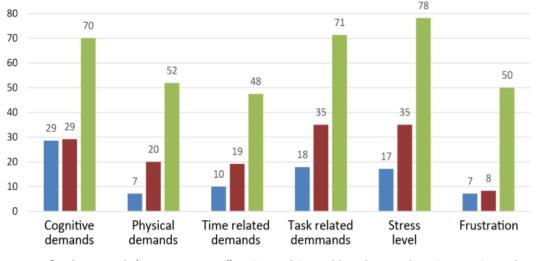




# **Rejuvenation Oriented Design ROD** User Integration and Usability

Evaluation collaborative work:

NASA TLX: average perceived task load levels (M) for test persons when operating the JRA in the collaborative assembly station by various, alternative control modes; N=21.



Semi-automatic (pre-programmed) Manual Control (touch screen) Gesture Control

Bundesministerium und Forschung un Control Mode 1: Semi-automatic



#### Control Mode 3: Gestures

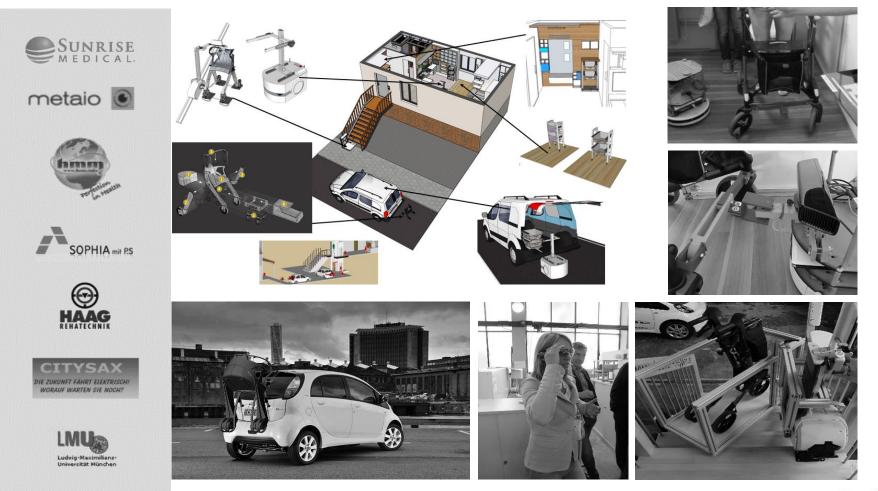


Control Mode 2: Manual





# PASSAge: Personalized Mobility Assistance and Service Systems in an Ageing Society





Chair of Building Realisation and Robotics | Automation, Robotics, Services in Construction



# **Rejuvenation Oriented Design ROD Personalized Mobility Assistance and Service Systems in an Ageing Society**









#### **In-House Mobility (PASSAge)**



#### STD

# **Single Task Devices**

#### for example: Transfer Robots

- Transferring is a **basic activity** of daily living
- Transferring is accounted as fundamental for performing tasks related to bathing, dressing, toileting, continence and feeding
- Transfer Robots support elderly people and care givers





#### **Humanoids and Exoskelettons**

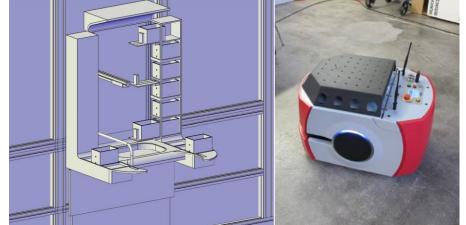
- Humanoids: function and motion capability are, in most cases, conceptually based on their equivalent in the human body
- Androids: not only interpret the human body's function but are designed to imitate human appearance and behavior
- Exoskelettons: combining the flexibility and intelligence of human beings with the speed and power of robotic systems



# ТШ

#### **R**ejuvenation **O**riented **D**esign **ROD** LISA: Living independently in Südtirol Alto-Adige























Technische Universität München





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### **REACH (Responsive Engagement of the Elderly promoting Activity and Customized Healthcare)**



LYNGBY-TAARBÆK KOMMUNE

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Chair of Building Realisation and Robotics | Automation, Robotics, Services in Construction

#### **Rejuvenation Oriented Design ROD**

# ТШ

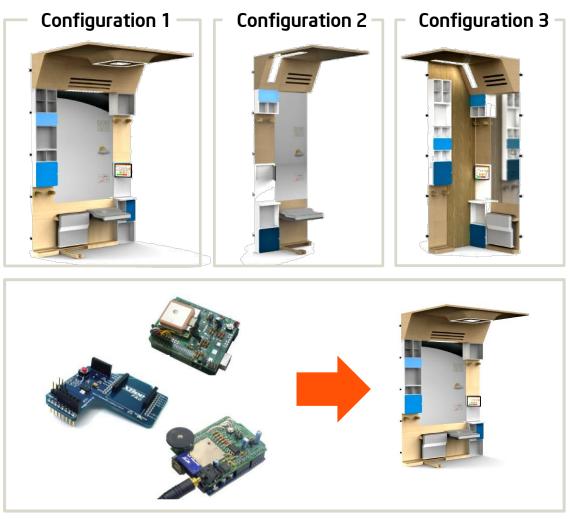
#### Integration of Mechatronics into "Furniture"



Integration of

**Mechatronics** 

and Services



Images: LISA Industry Consortium & Chair of Building Realisation and Robotics



### **Contactless/Ambient Sensing**





### **Contactless/Ambient Sensing**









#### Rejuvenation Oriented Design ROD LISA – Living Independently in Südtirol / Alto Adige LISA Terminal









**Reminder Module** 













### **Rejuvenation Oriented Design ROD Modularity for upgrading and personalization**

#### Modularity on "Room Level"



#### Modularity on "Wall Level"



Modular Functional Ad-ons



#### Modularity on Cabinet Level



Modularity on Software & Service Level





bc<sup>2</sup>7

Images: LISA Industry Consortium & Chair of Building Realisation and Robotics



# **Rejuvenation Oriented Design ROD** Rapid Installation / De-installation

Rapid De-installation (TUM br2, Germany)



#### Rapid Installation (Bozen, Italy)





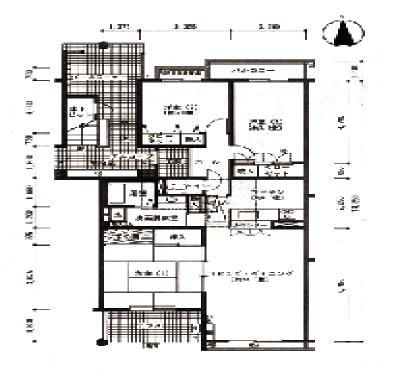
Images: LISA Industry Consortium & Chair of Building Realisation and Robotics







#### Age-based architecture in Japan









# ЛШ

#### **Rejuvenation Oriented Design ROD** LISA: Living independently in Südtirol Alto-Adige

















Human Factors become Henning Factors

www.br2.ar.tum.de